



## Feeler

Here will be a picture of the robot - so please submit a picture in a high resolution - min. 400x300pix<sup>2</sup>

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**Points of interest** The feeler scans its environment using the 35cm long antenna. It detects obstacles and explore its shape, if controlled accordingly, using a single acceleration sensor only.

### Technical details

**Type of machine** tactile sensor system, obstacle detection, feeler

**Size & weight** L: 40 cm x W: 1(3) cm x H:1 (10) cm, 200g

**Preferred substrate** no

### Additional material

For details see paper, Patent filed, free research licenses possible upon contact