

TARRY IIb



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Points of interest elastic joints, artificial neural net controller, decentral control of legs, decentral control of interleg-coordination, active tactile antennas, biologically inspired, stick insect like

Technical details

Type of machine hexapod walking machine

Size & weight L: 50 cm x W: 35 cm x H: 25 cm, 4 kg

Preferred substrate horizontal, grass, stairs

Additional material

detail pictures , video "tarryIIb_pos_feedback_single_test_leg.m1v"