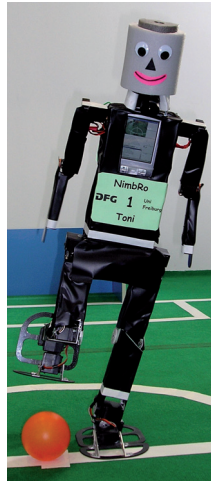


Robot data sheet



Toni



Developer Sven Behnke and Michael Schreiber
University of Freiburg, Germany
behnke@informatik.uni-freiburg.de
www.informatik.uni-freiburg.de/~behnke, www.nimbro.net

Points of interest Toni uses toes joints to over-extend its legs while walking
human-like with straight stance legs.

Technical details

Type of machine	Humanoid robot.
Size & weight	L: 15cm x W: 25 cm x H: 74 cm, 2.2kg
Preferred substrate	Horizontal carpet.

Additional material

Toni_Walking