

ZAR4



Developer

I. Boblan, R. Bannasch, A. Schulz, L. Miersch, H. Schwenk, J. Maschuw, I. Rechenberg
Technische Universität Berlin, EvoLogics, FESTO, Germany
boblan@bionik.tu-berlin.de
www.bionik.tu-berlin.de/user/boblan/research.html

Points of interest Anthropomorphic Robot, Five-finger Hand and Arm, Fluidic Muscle Driven Joints, Bionically Inspired Morphology and Physiology, Sensor Technology

Technical details

Type of machine Anthropomorphic Robot Hand and Arm

Size & weight L: 50 cm x W: 50 cm x H: 190 cm, 90kg

Preferred substrate flat, horizontal

Additional material