

Neuroinformatics and Cognitive Robotics Lab

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NICR Depth-Multi-Task Dataset Request

First Name and Last Name of Applicant

Research Institution

Address of Research Institution

ZIP Code, City, State

Country

Purpose of Using the Data Set

Contact E-Mail

Contact Telephone

Terms and Conditions of Usage

The NICR Depth-Multi-Task Dataset is publicly available for academic use only. Any non-academic use, including but not limited to commercial or military use, or actions related to the non-academic, commercial or military use of this dataset is strictly prohibited.

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Any publication using this dataset must reference to this website:
<https://www.tu-ilmenau.de/neurob/data-sets-code/depth-multi-task/>,
and this paper:

Daniel Seichter, Benjamin Lewandowski, Dominik Höchemer, Tim Wengefeld and Horst-Michael Gross

Multi-Task Deep Learning for Depth-based Person Perception in Mobile Robotics.

to appear: IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Las Vegas, IEEE 2020

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