

## Energy-efficient, adaptive suction gripper with sensor system

**System:** Monolithic, multiple folded, one fold uses a snap-through effect (mechanical instability), pneumatically driven, structure consists of conductive & non-conductive sections, energy-saving



Fig. 1 a) Suction gripper holder with an internal circuit; b) Suction gripper with conductive silicone on the inner side of the membrane; c) Suction gripper with a membrane made of conductive silicone; d) Suction gripper holder with two internal circuits; e) Suction gripper with three conductive structural sections

## Functional principle and optimization by finite element method (FEM):



Fig. 2.: a) suction gripper, holder & gripping object; b) successful & c) unsuccessful grasping process; geometry optimization via d) deformation behavior of the gripper & by means of e) a contact ring; f) snap-through characteristic

## Characteristics and advantages:

- Energy-efficient and resource-conserving (one component, suction medium does not get lost)
- Adaptation of the suction gripper: to different curvatures of the gripping object as well as to an
  inaccurate gripping object position (use of the snap-through effect)
- Adjustment of the transverse force stability during the gripping process by folding
- Actively controllable placing of the gripping object and specific overcoming of adhesion forces by convex concavity of the gripper base (in event of overpressure)
- Simple manufacture as well as minimal assembly and maintenance costs (monolithic design)
- Reduced hygienic risk (separation of suction and ambient substances)
- An inherent sensor system enables the evaluation of the gripping status and, on the other hand, the sorting of conductive and non-conductive gripping objects
- Detection of object contours and directions via a matrix arrangement of suction grippers



Fig. 3: a, b) Adaptation with different object curvature; c) in case of inaccurate object position; c) Depositing - active control

## Application:

The suction gripper is suitable for use in cleanrooms as well as in the packaging industry for gripping, manipulating and transporting medical and pharmaceutical products.

FG Nachgiebige Systeme, Prof. L. Zentner	Contact persons:	Zentner, Lena: lena.zentner@tu-ilmenau
TU Ilmenau, PF 100565, D-98684 Ilmenau		Griebel, Stefan: stefan.griebel@tu-ilmenau